



# Privacy Preserving Distributed Maximum Likelihood Estimation

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# Outline

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- Privacy preserving MLE for horizontally partitioned data
- Private preserving MLE for vertically partitioned data
- Secure multi-party protocol for function evaluation
- “Opt out” strategy
- Future work

# Distributed Maximum Likelihood Estimation

- Data  $\mathbf{x}^n = \{x_1, \dots, x_n\}$  generated from  $f(x; \theta)$
- The data are distributed across different agencies
  1. Horizontally partitioned
  2. Vertically partitioned

- The MLE is

$$\hat{\theta} = \arg \max_{\theta} l(\theta | \mathbf{x}^n)$$

- Goal: compute  $\hat{\theta}$  without sharing data between agencies

# Horizontally partitioned, exponential family

- Exponential family  $f(x) = b(x)\exp\{a(\theta)^T t(x) - c(\theta)\}$

- Log likelihood

$$l(\theta; \mathbf{x}^n) = \sum_{i=1}^n \log b(x_i) + \sum_{i=1}^n \{a(\theta)^T t(x_i) - c(\theta)\}$$

- The MLE is

$$\hat{\theta} = \arg \max_{\theta} a(\theta)^T \sum_{i=1}^n t(x_i) - nc(\theta)$$

- Secure summation of  $\sum_{i=1}^n t(x_i)$

# Horizontally partitioned, Newton Raphson

- Given the estimates  $\theta^{(s-1)}$  from the previous step, new estimate is

$$\theta^{(s)} = \theta^{(s-1)} - (D^2l(\mathbf{x}^n; \theta^{(s-1)}))^{-1} \nabla l(\mathbf{x}^n; \theta^{(s-1)}),$$

where  $D^2l()$  is the Hessian and  $\nabla l()$  is the gradient

- Assume  $\theta = \{\theta_1, \dots, \theta_k\}$ ,

$$\nabla l(\mathbf{x}^n; \theta^{(s-1)}) = \left( \sum_{i=1}^n \frac{\frac{\partial f(x_i; \theta)}{\partial \theta_1}}{f(x_i; \theta)}, \dots, \sum_{i=1}^n \frac{\frac{\partial f(x_i; \theta)}{\partial \theta_k}}{f(x_i; \theta)} \right)'_{\theta^{(s-1)}}$$

# Horizontally partitioned, Newton Raphson

- Locally, we can compute  $L_j$ ,  $1 \leq j \leq m$ , where

$$L_j = \left( \sum_{i=1}^{m_j} \frac{\frac{\partial f(x_i; \theta)}{\partial \theta_1}}{f(x_i; \theta)}, \dots, \sum_{i=1}^{m_j} \frac{\frac{\partial f(x_i; \theta)}{\partial \theta_k}}{f(x_i; \theta)} \right)'_{\theta^{(s-1)}}$$

- Similarly we can compute

$$H_j(h, l) = \sum_{i=1}^{m_j} \left( \frac{\frac{\partial^2 f(x_i; \theta)}{\partial \theta_h \partial \theta_l}}{f(x_i; \theta)} - \frac{\frac{\partial f(x_i; \theta)}{\partial \theta_h} \frac{\partial f(x_i; \theta)}{\partial \theta_l}}{f^2(x_i; \theta)} \right)_{\theta^{(s-1)}}$$

- The iteration step becomes

$$\theta^{(s)} = \theta^{(s-1)} - \left( \sum_{j=1}^m H_j \right)^{-1} \left( \sum_{j=1}^m L_j \right)$$



# Horizontally partitioned, Newton Raphson

- $H_j$  and  $L_j$  can be computed locally at each agency
- If  $m > 2$ , use secure summation to compute and share  $\sum_{j=1}^m H_j$  and  $\sum_{j=1}^m L_j$
- Potential drawbacks
  1.  $m$  has to be greater than 2
  2. Share more than necessary
- Compute  $(\sum_{j=1}^m H_j)^{-1}(\sum_{j=1}^m L_j)$  directly



# Horizontally partitioned, direct computation

- Without loss of generality, assume  $m = 2$
- Note that when  $m = 2$ , secure summation can't be applied
- Our goal: Compute  $(H_1 + H_2)^{-1}(L_1 + L_2)$  securely
- Approach: Solving linear equation system
- Denote  $X = (H_1 + H_2)^{-1}(L_1 + L_2)$ , the problem is equivalent to solve

$$(H_1 + H_2)X = (L_1 + L_2)$$





# Horizontally partitioned, direct computation

- Assume two agencies A and B
- A and B generate  $k \times k$  matrix  $M_1$  and  $M_2$  respectively, both with rank  $k/2$
- A sends  $M_1$  to B. B computes  $M_1H_2$  and  $M_1L_2$ , sends them to A

- A can produce the linear equation system

$$M_1(H_1 + H_2)X = M_1(L_1 + L_2)$$

- Symmetrically, B can produce

$$M_2(H_1 + H_2)X = M_2(L_1 + L_2)$$



# Horizontally partitioned, direct computation

- Sharing the two linear equation systems directly will reveal  $L_1$  and  $L_2$
- Solution: A and B generate full rank matrices  $T_1$  and  $T_2$  respectively
- Combine the following two linear equation systems to solve for  $X$

$$T_1 M_1 (H_1 + H_2) X = T_1 M_1 (L_1 + L_2)$$

$$T_2 M_2 (H_1 + H_2) X = T_2 M_2 (L_1 + L_2)$$



## Security analysis and discussion

- Agency A sent to B:  $M_2H_1$ ,  $M_2L_1$ ,  $T_1M_1(H_1 + H_2)$  and  $T_1M_1(L_1 + L_2)$
- A can check the rank of  $M_2$ . When  $K > 2$ ,  $H_1$  and  $L_1$  are not revealed
- Sharing of  $T_1M_1(H_1 + H_2)$  reveals  $T_1H_1$  to B, but not  $H_1$
- Protocol is symmetric
- Protocol works for  $m = 2$

# Vertically partitioned, independent variable

- Assume  $\mathbf{x}^n = \{x_1, \dots, x_n\}$ , where  $x_i = (x_i^1, \dots, x_i^p)$ . Each agency owns portion of the variables for all  $x_i$

- Assume  $f(x_i, \theta) = \prod_{s=1}^p f_s(x_i^s; \theta)$

- Log likelihood

$$l = \sum_{s=1}^p \left[ \sum_{i=1}^n \log f_s(x_i^s; \theta) \right]$$

- Compute locally at each agency and use secure summation or the direct computation protocol

# Vertically partitioned, exponential family

- Exponential family  $f(x) = b(x)\exp\{a(\theta)^T t(x) - c(\theta)\}$

- The MLE is

$$\hat{\theta} = \arg \max_{\theta} a(\theta)^T \sum_{i=1}^n t(x_i) - nc(\theta)$$

- Two agencies, A and B. A holds  $(x_{1,i}, \dots, x_{k,i})$ , and B holds  $(x_{k+1,i}, \dots, x_{p,i})$ ,  $1 \leq i \leq n$

- Need a protocol to compute

$$\sum_{i=1}^n t(x_{1,i}, \dots, x_{k,i}; x_{k+1,i}, \dots, x_{p,i}) \text{ securely}$$

# Vertically partitioned, secure two party computation

- Protocol to compute  $\sum_{i=1}^n t(x_{1,i}, x_{2,i})$  securely
- Step one. Agency A generate a vector of length  $s$ , among which the  $k$ th item  $x_{1,i}^k = x_{1,i}$ . The other  $s - 1$  items are random numbers
- Step two. A sends this vector to B, B computes  $t^1 = t(x_{1,i}^1, x_{2,i}), \dots, t^s = t(x_{1,i}^s, x_{2,i})$ . B generates a random number  $\epsilon_i$  and computes  $g_i^1 = t^1 - \epsilon_i, \dots, g_i^s = t^s - \epsilon_i$



# Vertically partitioned, secure two party computation

- Step three. Agency A obtains  $g_i^k$  using 1 out of  $s$  oblivious transfer
- Step four. Agency A has  $\sum_{i=1}^n g_i^k$  and Agency B has  $\sum_{i=1}^n \epsilon_i$ . Their sum gives  $\sum_{i=1}^n t(x_{1,i}, x_{2,i})$



## Vertically partitioned, secure two party computation

- Agency A obtains  $g_i^k$ . Since Agency does not know  $\epsilon_i$ , value of  $x_{2,i}$  is not revealed
- The quantities  $\sum_{i=1}^n g_i^k$  and  $\sum_{i=1}^n \epsilon_i$  are shared, but not the individual values
- Non symmetric due to 1 out of N oblivious transfer
- Communication cost  $n * s + n * L(s)$ .  $L(s)$  is the communication cost for 1 out of  $s$  oblivious transfer



# Vertically partitioned, Newton Raphson

- The gradient vector and Hessian matrix are

$$L = \left( \sum_{i=1}^n \frac{\frac{\partial f(x_i; \theta)}{\partial \theta_1}}{f(x_i; \theta)}, \dots, \sum_{i=1}^n \frac{\frac{\partial f(x_i; \theta)}{\partial \theta_k}}{f(x_i; \theta)} \right)_{\theta^{(s-1)}}$$

and

$$H = \sum_{i=1}^n \left( \frac{\frac{\partial^2 f(x_i; \theta)}{\partial \theta_h \partial \theta_l}}{f(x_i; \theta)} - \frac{\frac{\partial f(x_i; \theta)}{\partial \theta_h} \frac{\partial f(x_i; \theta)}{\partial \theta_l}}{f^2(x_i; \theta)} \right)_{\theta^{(s-1)}}$$

- Assume the functional form of  $H$  and  $L$  are shared, parameters can be updated using the last protocol

# “Opt out” strategies

- Utility and security considerations will cause agencies to opt out
- Size of dataset, numbers of variables
- Observed Fisher Information matrix

$$(\mathbf{J}(\theta))_{qh} = - \sum_{i=1}^n \frac{\partial^2}{\partial \theta_q \partial \theta_h} \log f(x_i; \theta).$$

Compare local  $J$  with the global  $J$

- Other utility and risk measures



## Conclusion

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- Privacy Preserving MLE for horizontally partitioned data using secure summation
- Privacy Preserving MLE for horizontally partitioned data using direct computation
- Privacy Preserving MLE for vertically partitioned data using secure function evaluation
- Opt out strategies



## Future work

- Private information propagation through iterations
- Constrained MLE

$$\hat{\theta} = \arg \max l(\theta; \mathbf{x}^n) \quad s.t. \quad C_j(\theta) \quad 1 \leq j \leq m,$$

where  $C_j(\theta)$  are the parameter constraints each agency follows and can not be shared

- General constrained optimization problems with privacy assurance
- Connection between privacy preserving distributed computing and SDL