# Robust inference in two-phase sampling with application to unit nonresponse

#### David Haziza and Jean-François Beaumont

Université de Montréal and Statistics Canada

International Total Survey Error Workshops 2011

Quebec, Canada

June 21, 2011

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## Outline of the presentation

- 1. Introduction
- 2. Measuring the influence: the conditional bias
- 3. Robust estimators
- 4. Application to unit nonresponse
- 5. Simulation study
- 6. Concluding remarks

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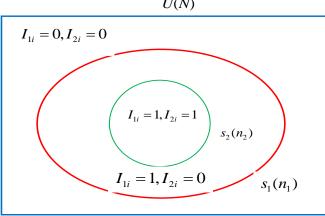
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• In the remaining, we assume that the two-phase design satisfies the invariance property

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$$E_1 E_2(\hat{Y}_{DE} | \mathbf{I}_1) = Y$$

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$$\hat{Y}_{DE} - Y = \underbrace{(\hat{Y}_E - Y)}_{\text{first-phase}} + \underbrace{(\hat{Y}_{DE} - \hat{Y}_E)}_{\text{second-phase}}$$
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- How to construct a robust estimator to the presence of influential units? Single phase designs: Beaumont, Haziza and Ruiz-Gazen (2011).

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- Influence of sampled unit  $i \in s_2$ :

$$\begin{split} B_i^{DE}(I_{1i} = 1, I_{2i} = 1) &= E_1 E_2 (\hat{Y}_{DE} - Y | \mathbf{I}_1, I_{1i} = 1, I_{2i} = 1) \\ &= E_1 (\hat{Y}_E - Y | I_{1i} = 1) \\ &+ E_1 E_2 (\hat{Y}_{DE} - \hat{Y}_E | \mathbf{I}_1, I_{1i} = 1, I_{2i} = 1) \end{split}$$

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• Arbitrary two-phase design:

$$B_{i}^{DE}(I_{1i} = 1, I_{2i} = 1) = \underbrace{\sum_{j \in U} \left(\frac{\pi_{1ij}}{\pi_{1i}\pi_{1j}} - 1\right) y_{j}}_{\text{Influence of unit } i \text{ on the first-phase error}} \\ + \underbrace{\sum_{j \in U} \frac{\pi_{1ij}}{\pi_{1i}\pi_{1j}} \left(\frac{\pi_{2ij}}{\pi_{2i}\pi_{2j}} - 1\right) y_{j}}_{\text{Influence of unit } i \text{ on the second-phase error}} \\ = \underbrace{\sum_{j \in U} \left(\frac{\pi_{ij}^{*}}{\pi_{i}^{*}\pi_{j}^{*}} - 1\right) y_{j}}_{\text{Total influence of unit } i}$$

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• SRSWOR/SRSWOR: 
$$\pi_i^* = \frac{n_1}{N} \times \frac{n_2}{n_1} = \frac{n_2}{N}$$
  
 $B_i^{DE}(I_{1i} = 1, I_{2i} = 1) = \frac{N}{(N-1)}(\frac{N}{n_1} - 1)(y_i - \bar{Y})$   
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June 21, 2011 12 / 22

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• Poisson sampling/Poisson sampling:

$$B_i^{DE}(I_{1i} = 1, I_{2i} = 1) = \left(\frac{1}{\pi_{1i}} - 1\right) y_i + \frac{1}{\pi_{1i}} \left(\frac{1}{\pi_{2i}} - 1\right) y_i$$
$$= \left(\frac{1}{\pi_i^*} - 1\right) y_i$$

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June 21, 2011 12 / 22

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#### A robust version of the double expansion estimator

• Following Beaumont, Haziza and Ruiz-Gazen (2011), we obtain

$$\hat{Y}_{DE}^{R} = \hat{Y}_{DE} - \sum_{i \in s_{2}} \hat{B}_{i}^{DE}(I_{1i} = 1, I_{2i} = 1) + \sum_{i \in s_{2}} \psi \left\{ \hat{B}_{i}^{DE}(I_{1i} = 1, I_{2i} = 1) 
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• Example of  $\psi$ -function:

$$\psi\left(t
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• c: tuning constant

## A robust version of the double expansion estimator

• Following Beaumont, Haziza and Ruiz-Gazen (2011), we obtain

$$\hat{Y}_{DE}^{R} = \hat{Y}_{DE} - \sum_{i \in s_{2}} \hat{B}_{i}^{DE}(I_{1i} = 1, I_{2i} = 1) + \sum_{i \in s_{2}} \psi \left\{ \hat{B}_{i}^{DE}(I_{1i} = 1, I_{2i} = 1) \right\}$$

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- c: tuning constant
- Special case: single-phase sampling; i.e.,  $I_{2i} = 1$  for all  $i \Rightarrow \hat{Y}_{DE}^R$  reduces to the robust estimator proposed by Beaumont, Haziza and Ruiz-Gazen (2011).

• *s*<sub>2</sub>: set of respondents

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• Influence of a responding unit:

$$B_i^{PSA}(I_{1i} = 1, I_{2i} = 1) = \underbrace{\sum_{j \in U} \left(\frac{\pi_{1ij}}{\pi_{1i}\pi_{1j}} - 1\right) y_j}_{\text{Influence of unit } i \text{ on the sampling error}} \underbrace{y_j + \underbrace{\pi_{1i}^{-1} \left(\pi_{2i}^{-1} - 1\right) y_i}_{\text{Influence of unit } i \text{ on the nonresponse error}}$$

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• Robust version of  $\hat{Y}_{PSA}$ 

$$\begin{split} \hat{Y}_{PSA}^{R} &= \hat{Y}_{PSA} - \sum_{i \in s_{2}} \hat{B}_{i}^{PSA} (I_{1i} = 1, I_{2i} = 1) \\ &+ \sum_{i \in s_{2}} \psi \left\{ \hat{B}_{i}^{PSA} (I_{1i} = 1, I_{2i} = 1) \right\} \end{split}$$

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- Generate nonresponse: Bernoulli trials with probability  $\pi_{2i}$ , where

$$\pi_{2i} = \frac{1}{\exp(\alpha_0 + \alpha_1 x_i)}$$

• Global response rate: 70%

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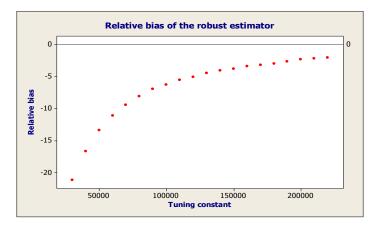
• Relative Efficiency with respect to the nonrobust estimator:

$$RE(\hat{Y}_{PSA}^{R}) = rac{MSE(\hat{Y}_{PSA}^{R})}{MSE(\hat{Y}_{PSA})}$$

• Note:  $\hat{Y}_{PSA}$  has negligible bias

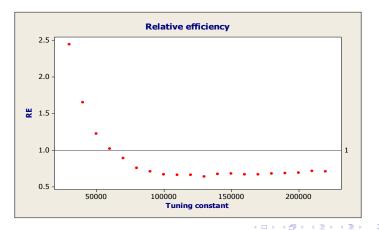
June 21, 2011 19 / 22

# Relative bias of the robust estimator (5% contamination)



June 21, 2011 20 / 22

# Relative efficiency with respect to the nonrobust estimator (5% contamination)



David Haziza and Jean-François Beaumont () Robust inference in two-phase sampling

June 21, 2011 21 / 22

 Conditional bias: measure of influence that takes account of the sampling design, the parameter to be estimated and the estimator

# Concluding remarks

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- Results can be extended to the case of calibration estimators ⇒ important in the unit nonresponse context since weight adjustment procedures by the inverse of the estimated response probabilities are generally followed by some form of calibration
- Requires further investigations:
  - Choice of the tuning constant
  - MSE estimation: reverse framework for variance estimation?